

Non linear dynamics of the glottis : Phase Portraits and Lyapunov Exponents

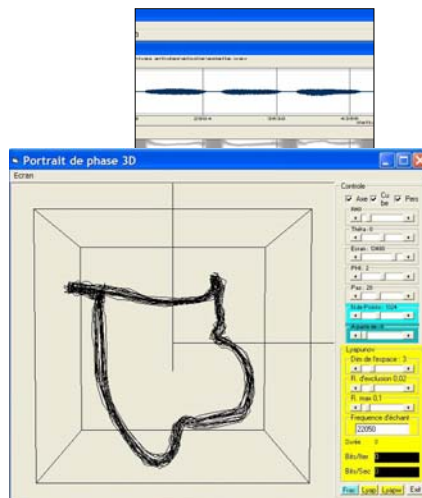
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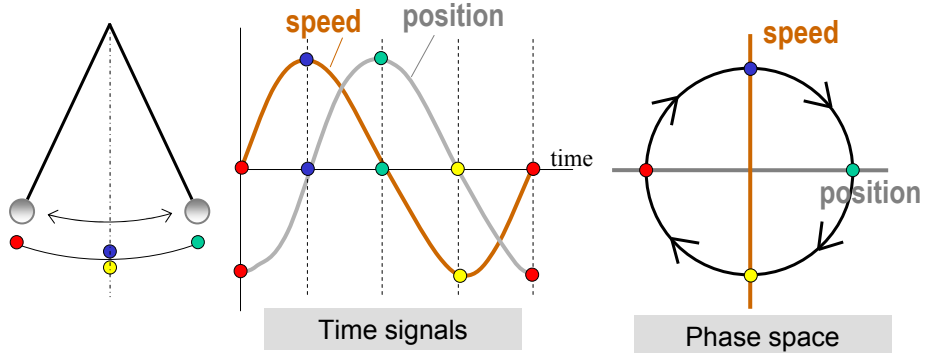
Signal Analysis

Tools available

- Wave display
- Spectrogram
- Jitter
- Cepstrum
- Autocorrelation
- Phase portraits

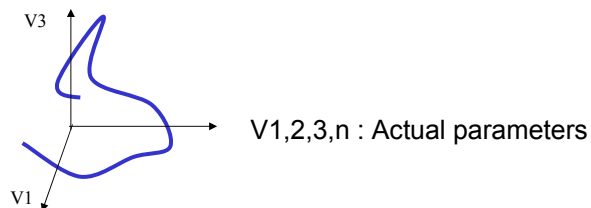
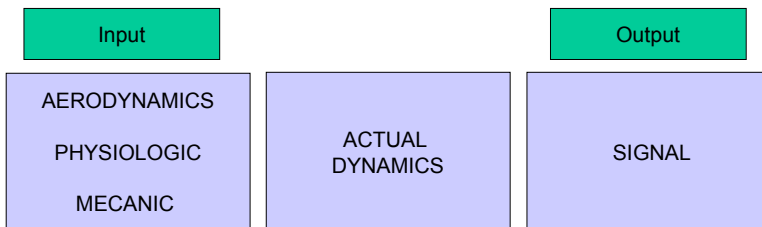


Construction of a Phase Portrait : Pendulum

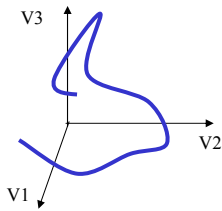


- Knowledge of the position and the speed of the pendulum is sufficient to characterize its dynamics completely
- Succession of the states of a periodic system describes a closed curve in the phase space

Phase Portrait : representation of the dynamics of a system



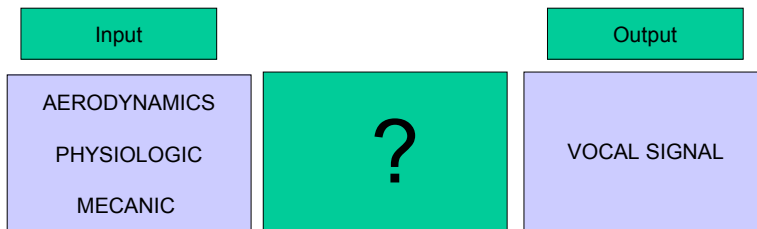
Construction of a Phase Portrait : GLOTTIS



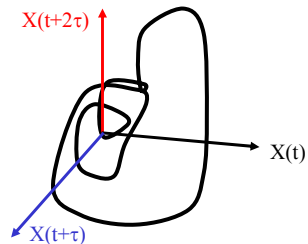
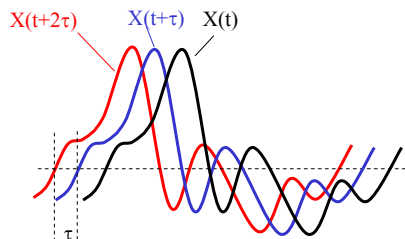
$V_{1,2,3}$: Unknown actual parameters



TIME DELAY METHOD
D Ruelle, F Takens

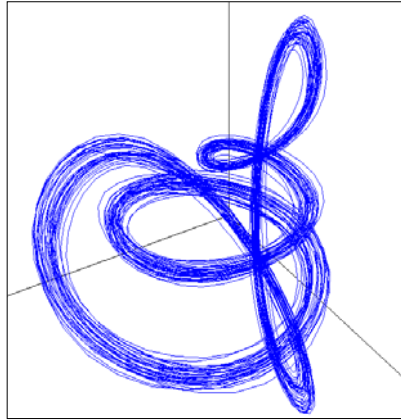
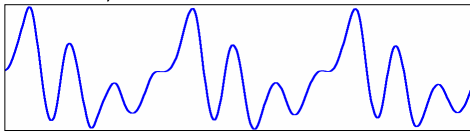
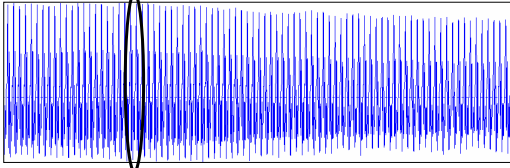


Construction of a Phase Portrait : time delay method



Example 1 : normal voice

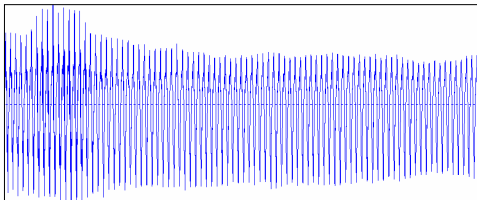
Sample of sustained Vowel/a/



-Quasi-periodic attractor

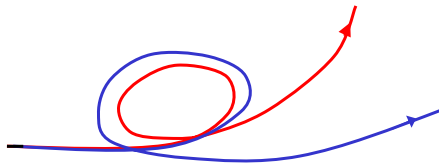
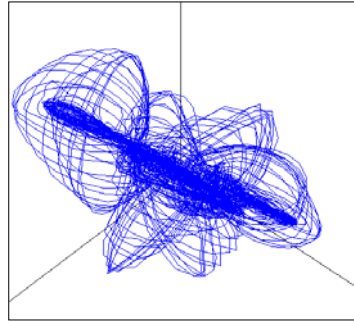
-Closed-loop trajectories

Example 2 : severe dysphonia



Quantification of a Phase Portrait

- Fractal dimensions
 - Number of degrees of freedom
- Lyapunov Exponent
 - Divergence of initially close trajectories
 - Divergence : Sensitivity to Initial Conditions (SIC)



Determination of Lyapunov exponent

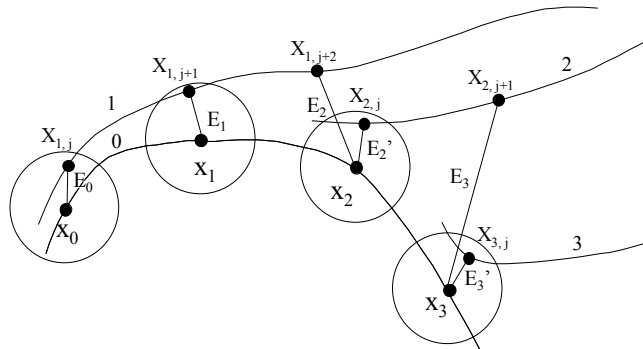
After n iterations, error amplification factor would be:

$$\left| \frac{E_n}{E_0} \right| = \left| \frac{E_n}{E_{n-1}} \right| \left| \frac{E_{n-1}}{E_{n-2}} \right| \dots \left| \frac{E_1}{E_0} \right|$$

Lyapunov coefficient characterizes the logarithm of increase in relative error during iteration

$$\lambda = \frac{1}{n} \sum_{k=1}^n \log \left| \frac{E_k}{E_{k-1}} \right| \text{ for } n \rightarrow \infty ; E_0 \rightarrow 0$$

Choice of neighbor points of the reference trajectory



In an experimental series, the main problem is selection of neighboring points in the reference orbit.

Signal instability : clinical measurements

